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comments and bulletins
concerning your
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BULLETIN #11
April 30, 1979

This month's Transactor contains an excellent article by Brad Templeton on Pet interrupts. Also information on a PET to IBM selectric interface.

This is also the final issue of Volume 1. A subscription form for Volume 2 follows. When submitting the form, please address it to Commodore's Agincourt address followed by 'Attn. The Transactor'.

Transactor Volume 2

Yes it's renewal time. Although your Volume 1 subscription covers one more issue, here is the Volume 2 subscription form. The Transactor operates on a break-even basis. Therefore the cost of "The Transactor Volume 2" will be \$15.00.

Recently I have received various requests regarding article subjects. If you have a subject idea you and other PET users would like to see discussed in future Transactors, please include it at the bottom of the order form.

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IDEAS & COMMENTS.....

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Convert Upper to Lower Case

The following is a program that will convert all upper case text to lower case. However, keep in mind that any graphics above the alphabetic keys will now be unusable if they are to appear simultaneously with lower case letters.

```
59030 FOR T=1024 TO 8006-FRE(0):A=PEEK(T)
59031 ON Z GOTO 59034,59037
59032 IF A=153 OR A=178 THEN Z=1
59033 NEXT
59034 IF A=34 THEN Z=2:NEXT
59035 IF A=58 OR A=0 THEN Z=0
59036 NEXT
59037 IF A 64 AND A 91 THEN POKE T,A+128
59038 B=PEEK(T+1):IF B=34 OR B=0 THEN Z=0
59039 NEXT:END
```

When writing the program use no spaces. The program will convert strings and PRINT statements but will not affect DATA statements. Also, it may terminate with a '?NEXT WITHOUT FOR ERROR IN 59036' but that's OK.

Of course you need not use the same line numbers. They were chosen due to their unusualness. The program was then recorded using the UNLIST routine in Transactor #7. It can then be merged with other programs with a good chance of not interfering with other program lines.

Karl J.

INTERRUPTS ON THE COMMODORE PET

(c) 1979 Brad Templeton

One of the most important features of the COMMODORE PET operating system is the use of interrupts. They are used to reset the PET, and they handle most of the tape and all of the keyboard i/o. This article will provide an introduction to interrupts on the 6502 (The PET's cpu) and a description of how the PET handles them. For your information, pseudo source listing is provided for the interrupt software of the PET, as produced by my disassembler.

Under normal conditions, a processor executes machine code in a linear fashion. It moves through memory, obtaining instructions (which can be one, two or three bytes long) and executing them. Sometimes, certain programmed instructions cause jumps to other places, just like GOTO and GOSUB of basic. To make a machine more flexible, however, interrupts are provided to do jobs that would be very expensive to do in software.

Essentially, an interrupt is controlled by a line right into the processor. When the processor detects the correct voltage on this line, an interrupt may be generated. First, in order to simplify matters, the processor finishes the instruction it is presently carrying out. Then, if the in-

interrupt is ok (interrupts can be masked). The processor saves the program location it was at, and the contents of its flags onto the stack. It then goes to a special reserved area of memory (in ROM on the PET) and pulls out two bytes indicating what location it should start executing from. It then goes there and executes machine code until the instruction RTI (Return from Interrupt \$40) is encountered. It then goes back to the stack and restores its flags, and loads the location it saved to the instruction counter. It then goes and executes the code after where it stopped as though nothing had occurred. (If the interrupt program was correctly written)

On the 6502, three types of hardware interrupts can occur, as well as a fourth special type. The locations they branch to are kept in byte pairs called vectors at the end of memory. One of these interrupts, NMI or Non Maskable Interrupt, can not be used on the PET. Its vector, \$FFFA-B, points to \$CA60, which is the middle of a subroutine. The line for this is also fixed off by a resistor on the pc board. Later PETs may plan to include this.

The interrupt called for power up is named RES. It branches to a routine which sets up basic and the operating system. It also, through what I consider to be one of the PET's worst design flaws, branches to the routine to destructively test how much memory is in the machine. At the very start, it also tests the condition of the diag-

nostic sense (MSB of \$E810), and goes to the diagnostic routine if this is set. RES is fired by power up, or by grounding pin 27 on the bottom of your memory expansion bus. If you set it by touching that pin, it does not clear memory below \$400, so programs there (the tape buffers) are safe. This is, unfortunately, a very small area. It vectors through \$FFFC-D.

The general use, hardware interrupt is the IRQ. IRQ vectors through \$FFFE-F, as does BRK. This points to location \$E66B in the PET. It is generated every 60th of a second by the tv hardware, and can also be generated from the memory expansion bus, on pin 28. It is also connected to the 6522 versatile interface adaptor. I will discuss the 60 per second interrupts here in detail. For information of generation by the 6522 (there is another whole article's worth of material in there) you can write MOS^① for the manual on it. Interrupts can be generated from it at exactly timed intervals, and by certain i/o conditions on the user port and IEEE bus. The exactly timed intervals are used to send precise frequency signals to the tape. (In fact, the 6522 is the PET's tape interface!)

The 60 per second interrupts do the following:

- Scan the keyboard, checking for new keys and decoding them.
- Increment the real time clock, and check for midnight
- Flash the cursor if it is on. (\$0224=0)
- Test tape recorder status for stop-start

Copy a byte for the break key test.

Whatever else you want them to do.

When the IRQ occurs, the code at \$E668 (see source) saves the processor register A, X and Y on the stack. It then checks, by loading back from the stack, the flags, to see if the BRK flag was set. The BRK, a software IRQ, vectors through the same place, but sets the BRK flag. This is handy to test what type of interrupt occurred. It then does a jump indirect to one of two places in RAM (\$219 or \$21B) depending on the type of interrupt.

Normally, the RAM IRQ vector is set to \$E685, which is the standard IRQ code. BRK has no default setting. The small piece of code you see after the JMP indirects is the return code, which restores the registers and does the RTI. The first thing INT_CODE does is the JSR INCR_CLOCK which increments the clock and copies the PIA register the break key test uses. When Steve Punter of Mississauga saw this with the disassembler, he devised an ingenious way to disable the BREAK key of the PET. By telling the PET to branch to \$E688 instead of \$E685 by means of a POKE 537, 136 statement, the PET bypasses the INCR_CLOCK subroutine, and does not test the break key. (Note INCR_CLOCK passes through a JMP vector table in high ROM at \$FFEA) This has the side effect of turning off the real time clock. When this statement is not used the clock proceeds normally. After it is updated, it is compared with a three byte table that con-

tains the value for midnight. If it is midnight on the clock, it is zeroed. The PET also keeps a secondary clock just after the main one. This is used for calibrating the real time clock. About every 6 seconds, this clock reaches a special limit, and when it does, it is zeroed, and the main clock is not incremented on this cycle. This is because the interrupt generator runs slightly faster than exactly 60 times per second. Even with this compensation, you may have noticed the clock is a few seconds off after several hours of PET operation. If they had used the 60 hz ac power line for the interrupt, it would have been more accurate, but that would have caused problems for PETs sold abroad.

After doing the clock, it proceeds to flash the cursor, once every third of a second, if the location FLASHING (\$224) is set to zero. (POKE 548,0 in a program turns the cursor on, but with some bugs - try it and see.) It does it with a very silly method that has no apparent purpose, instead of the standard method, a EOR \$80. It then sets up two keyboard test locations.

In using your PET, you may have noticed that if the tape drive is stopped by the machine itself, that you can push stop and play and the motor will run again. This is handled by the section of code at \$E6CD. After this comes the keyboard interpretation routines. The method of decoding the keyboard PIA has already been published in your

PET manual, and in PET user notes, so I will not dwell on it here. Once it has the matrix coordinate of the key, it waits for it to stabilize, to avoid bounce and repeating letters. (The TRS-80 does this poorly). It then converts the matrix number to an ascii character through the table at \$E75C. (You can use this table in your programs, if you want to account for how long a key is held down - a great real time feature!) It then puts the key in the correct place in the keyboard buffer starting at \$20F. Finally it goes back.

WHAT YOU CAN DO

Because the PET IRQ goes through RAM, it is one of the main links you have that can give you operating system control. You can insert your own programs before and after the interrupt code to have your PET do two jobs at once, like handle i/o while running basic. I have used interrupts to write programs to:

Interpret the PET keyboard and the full sized keyboard I attached to the PET like a regular keyboard.

Provide functions like repeat after a certain period of time and shift lock.

Turn the ! key to a statement number key, so that it would provide a line number 10 higher with every push.

Have upper case letter keys print out as full basic keywords.

Display whole pages of PET memory constantly on the screen.

Provide a non-destructive reset that works in special cases.

Much more is possible.

To use your own programs, you merely set them up in some convenient location (machine code only), preferably starting at location that ends in \$85, such as \$385 in the second tape buffer. Something located there can then be started with a POKE538,3 and stopped with POKE 538,230, rather than having to write a special machine language program that disables the interrupt with SEI, changes the locations, and enables the interrupt with CLI. You do not

need to disable if you are only changing one byte of the location. Put some code there and follow it with a JMP \$E685. This way it does your code and proceeds on to do its own. If you put in the following series:

```
EE 50 80 4C 85 E6
```

starting at \$385 (901 base 10), and initiate it with POKE 538,3 you will see a byte on the screen constantly increasing in "value", once every 60th of a second. The PET will also be doing everything else as usual. The following code:

```
A2 00 BD 00 00 9D 50 80 E8 D0 F7 4C 85 E6
```

will dump a page of memory on the screen constantly. You can poke 905 with the page you wish to examine. Try 0,1,2,4,31,232. It starts with page 0. When scanning page 0, move the cursor and see what happens.

While doing this, you may have noticed that there is no flicker whatsoever on the screen despite the massive amount of writing to it being done. (Far faster than BASIC printing). This is because the interrupt is fired by the screen scan signal, and the screen is doing nothing shortly after the interrupt goes. This is also why the flashing cursor will never "snow" the screen. You can store almost half a screen without "snow" this way.

Sometimes it is important to put code in after the interrupt code of the PET. This can be done by manipulation of the stack, and is necessary for programs like the statement

numberer or keyword printer I included in my list above. I have included some code you can put in to allow you to do this. >PRDG means the high order byte of where your post interrupt code starts and PRDG is the low order byte. PCLO and PCHI are two locations for storing the correct pc you can use. The program works by altering the stack, so that the PET goes to your program when it RTIs. The second part of the program, which finishes your routine off (GOBACK) resets the stack and restores the proper program counter and machine registers. You should be able to have a lot of fun with it.

It should be noted that probably the only reason the IRQ vector is in RAM is that the PET does change it for tape i/o routines. There is a table of possible vectors starting at \$FD28 in the rom, and the table ends with the standard vector \$E685. If you ever change the high order byte of the IRQ RAM vector, you must reset it before tape i/o is done. If you don't, the PET will reset it anyway, but the tape i/o may not be done, and you may crash your PET.

Incidentally, the disassembler was written in the system language B (a very nice, much improved BCPL) here at the University of Waterloo where I go to school and work for the Mathematics Faculty Computing Facility. This article was also prepared and formatted on the same Honeywell 66/60. Many of the labels used in the disassembly were provided through the massive effort of examining the PETs ROMs done

by Jim Butterfield of Toronto. My next article for the Transactor will be on programming interactive games for the PET.

- ① The 6522 Data Sheets (24 pgs.) and other MOS publications are available through dealers.

Here is the code for the interrupts on the PET

```

E66B 48          INTERRUPT  PHA
E66C 8A          TXA
E66D 48          PHA
E66E 98          TYA
E66F 48          PHA
E670 8A          TSX
E671 BD 04 01    LDA $104,X
E674 29 10        AND #$10
E676 F0 03        BEQ $E67B
E678 6C 18 02    JMP [BRK_LOW]
E67B 6C 19 02    JMP [IRQ_LOW]
E67E 68          RETURN_INT PLA
E67F A8          TAY
E680 68          PLA
E681 AA          TAX
E682 68          PLA
E683 40          RTI

E684 60          RTS

E685 20 EA FF    INT_CODE JSR INCR_CLOCK
E688 AD 24 02    LDA FLASHING
E68B D0 23        RNE $E680
E68D CE 25 02    DEC C_TIMER
E690 D0 1F        RNE $E680
E692 A9 14        LDA #$14
E694 8D 25 02    STA C_TIMER
E697 A4 F2        LDY C_COLUMN
E699 4E 27 02    LSR C_STATE
E69C B1 E0        LDA (C_ROWADR),Y
E69E 80 06        RCS $E6A6
E6A0 EF 27 02    INC C_STATE
E6A3 8D 26 02    STA CHAR_UND_C
E6A6 0A          ASL
E6A7 80 03        RCS $E6AC
E6A9 38          SEC
E6AA 80 01        RCS $E6AD
E6AC 18          CLC
E6AD 6A          ROR
E6AE 91 E0        STA (C_ROWADR),Y
E6B0 A2 FF        LDX #$FF
E6B2 8E 23 02    STX KEY_IMAGE
E6B5 F8          INX
E6B6 8E 04 02    STX SHIFT_FL
E6B9 A2 50        LDX #$50
E6BB AD 10 E8    LDA PIA1
E6BE 29 F0        AND #$F0

```

```

E6C0 8D 10 E8
E6C3 A0 00
E6C5 AD 10 E8
E6C8 0A
E6C9 0A
E6CA 0A
E6CB 10 07
E6CD 8C 07 02
E6D0 A9 3D
E6D2 D0 07
E6D4 AD 07 02
E6D7 D0 05
E6D9 A9 35
E6DB 8D 13 E8
E6DE 90 0A
E6E0 8C 08 02
E6E3 AD 40 E8
E6E6 09 10
E6E8 D0 0A
E6EA AD 08 02
E6ED D0 08
E6EF AD 40 E8
E6F2 29 EF
E6F4 8D 40 E8
E6F7 A0 08
E6F9 AD 12 E8
E6FC CD 12 E8
E6FF D0 F6
E701 4A
E702 B0 05
E704 48
E705 20 3F E7
E708 68
E709 CA
E70A F0 08
E70C 88
E70D D0 F2
E70F FE 10 E8
E712 D0 E3
E714 AD 23 02
E717 CD 03 02
E71A F0 20
E71C 8D 03 02
E71F AA
E720 30 1A
E722 BD 5B E7
E725 4E 04 02
E728 90 02
E72A 09 80
E72C AE 0D 02
E72F 9D 0F 02
E732 E8
E733 E0 0A
E735 D0 02

```

```

STA PIA1
LDY #$0
LDA PIA1
ASL
ASL
ASL
RPL $E6D4
STY C1_STAT
LDA #$3D
BNE $E6DB
LDA C1_STAT
BNE $E6DE
LDA #$35
STA PIA1_B4
BCC $E6EA
STY C2_STAT
LDA PORT_B
ORA #$10
BNE $E6F4
LDA C2_STAT
BNE $E6F7
LDA PORT_B
AND #$EF
STA PORT_B
LDY #$8
LDA KB_ROWIN
CMP KB_ROWIN
BNE $E6F7
LSR
BCS $E709
PHA
JSR DECODE_KBD
PLA
DEX
BEQ $E714
DEY
BNE $E701
INC PIA1
BNE $E6F7
LDA KEY_IMAGE
CMP KEY_DOWN
BEQ $E73C
STA KEY_DOWN
TAX
BMI $E73C
LDA $E75B,X
LSR SHIFT_FL
BCC $E72C
ORA #$80
LDX KEYCOUNT
STA KEY_BUFF,X
INX
CPX #$A
BNE $E739

```

```

E737 A2 00          LDX  #$0
E739 8E 0D 02      STX  KEYCOUNT
E73C 4C 7E E6      JMP  RETURN_INT
E73F 8D 5B E7      DECODE_KRD LDA  $E75B,X
E742 D0 07          BNE  $F748
E744 A9 01          LDA  #$1
E746 8D 04 02      STA  SHIFT_FL
E749 D0 10          BNE  $E75B
E74B C9 FF          CMP  #$FF
E74D F0 0C          BEQ  $E75B
E74F C9 3C          CMP  #$3C
E751 D0 05          BNE  $E758
E753 2C 11 E8      BIT  PIA1 + 1
E756 30 03          BMI  $E75B
E758 8E 23 02      STX  KEY_IMAGE
E75B 60            RTS

```

```

F736 AD 05 02      UPDATE_CLK LDA  CLOCK_2
F739 69 01          ADC  #$1
F73B 8D 05 02      STA  CLOCK_2
F73E 90 03          BCC  $F743
F740 EE 06 02      INC  CLOCK_2 + 1
F743 C9 6F          CMP  #$6F
F745 D0 07          BNE  $F74E
F747 AD 06 02      LDA  CLOCK_2 + 1
F74A C9 02          CMP  #$2
F74C F0 26          BEQ  $F774
F74E EE 02 02      INC  M_CLOCK + 2
F751 D0 08          BNE  $F75B
F753 EE 01 02      INC  M_CLOCK + 1
F756 D0 03          BNE  $F75B
F758 EE 00 02      INC  M_CLOCK
F75B A2 00          LDX  #$0
F75D 8D 00 02      LDA  M_CLOCK,X
F760 DD 88 F7      CMP  $F788,X
F763 90 17          BCC  $F77C
F765 E8            INX
F766 F0 03          CPX  #$3
F768 D0 F3          BNE  $F75D
F76A A9 00          LDA  #$0
F76C 9D FF 01      STA  $1FF,X
F76F CA            DEX
F770 D0 FA          BNE  $F76C
F772 F0 08          BEQ  $F77C
F774 A9 00          LDA  #$0
F776 8D 05 02      STA  CLOCK_2
F779 8D 06 02      STA  CLOCK_2 + 1
F77C AD 12 E8      LDA  KB_ROWIN
F77F CD 12 E8      CMP  KB_ROWIN
F782 D0 F8          BNE  $F77C
F784 8D 09 02      STA  PIA_COPY
F787 60            RTS

```

Here is the source for the post interrupt code program

```
START      LDA    $105,X          GET
           STA    PCLO            PROGRAM
           LDA    $106,X          COUNTER AND
           STA    PCHI            STORE IT
           LDA    PROG            PUT IN YOUR
           STA    $105,X          OWN CODE
           LDA    >PROG           LOCATION
           STA    $106,X
           JMP    $E685           DO NORMAL INTERRUPT
GOBACK     REM    THIS CODE GOES AFTER YOUR CODE, TO RETURN
           LDA    PCHI            RESTORE
           PHA    OLD
           LDA    PCLO            LOCATION
           PHA
           TSX
           DEX                    RESET
           DEX                    STACK
           DEX
           DEX
           TXS
           JMP    $E65E           DO RTI
```


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